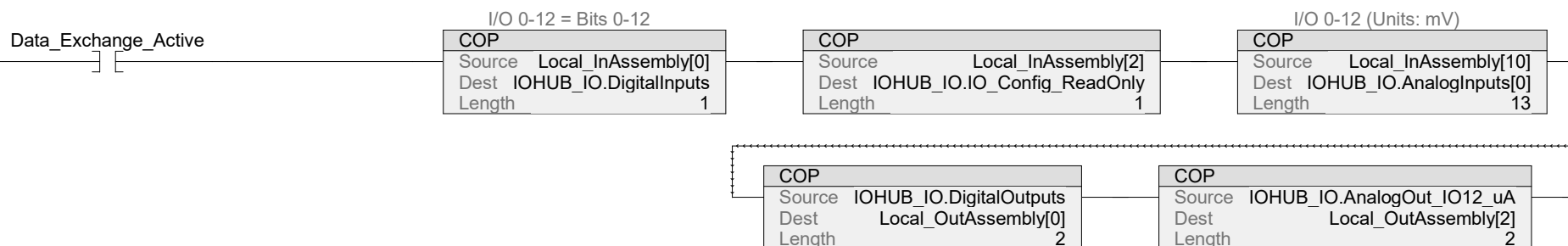


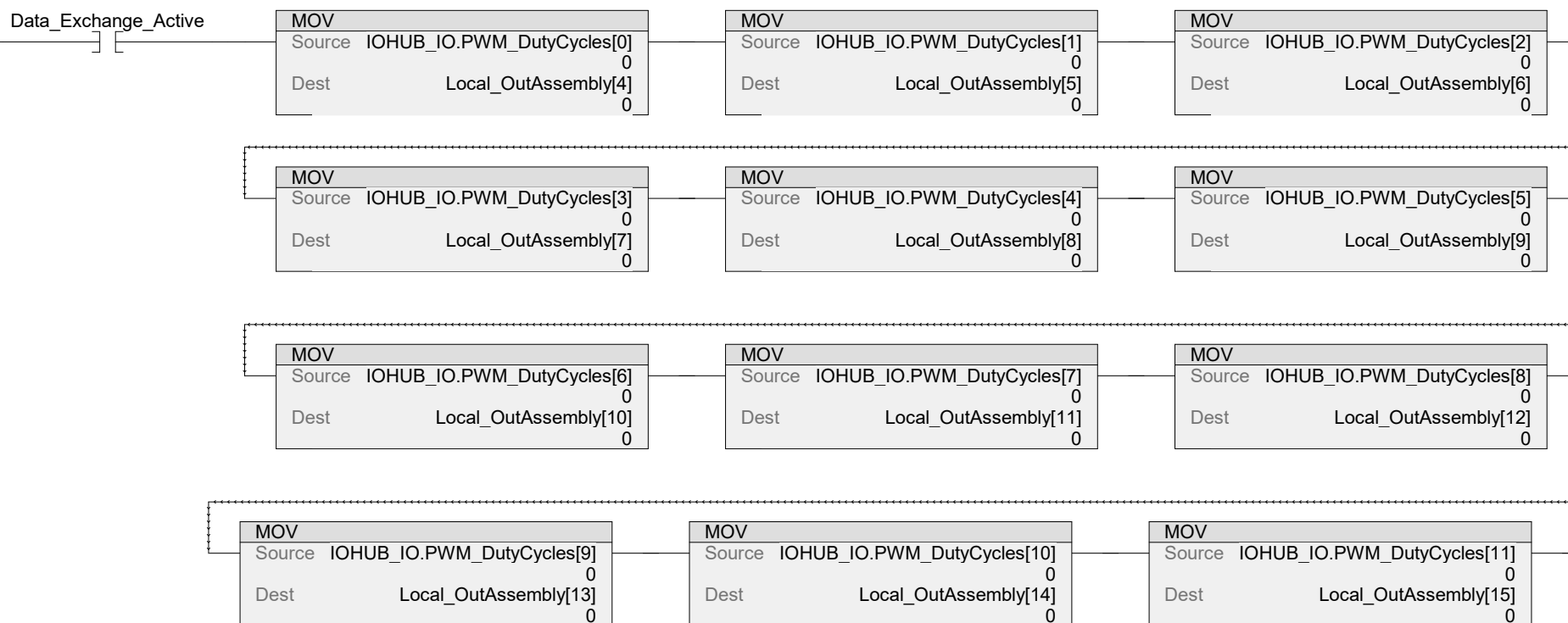
Copy the input assembly I/O data from the local version of the input assembly into the IO\_HUB\_IO UDT and copy the I/O output data from the IO\_HUB\_IO UDT to a local version of the output assembly.

2



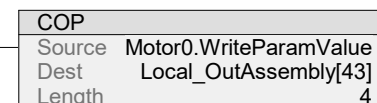
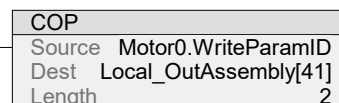
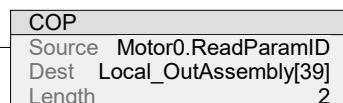
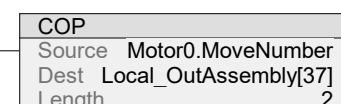
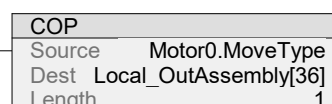
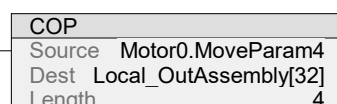
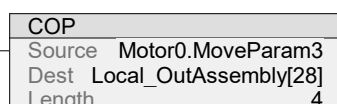
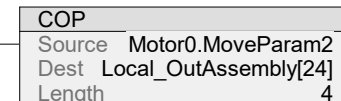
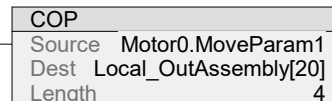
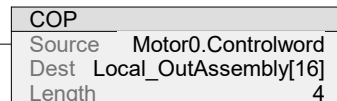
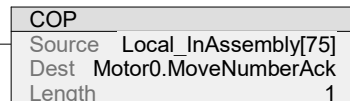
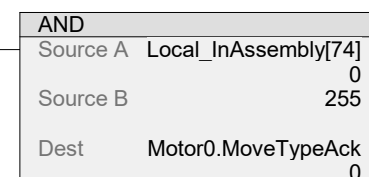
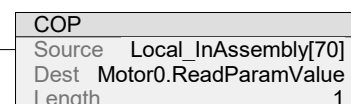
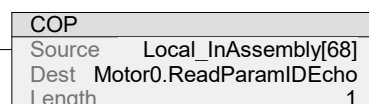
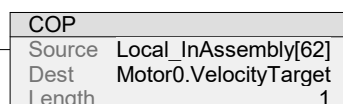
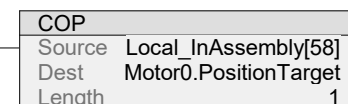
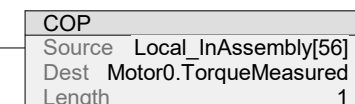
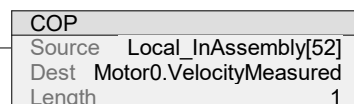
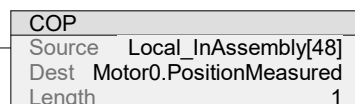
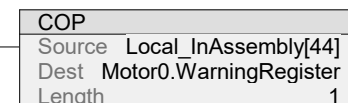
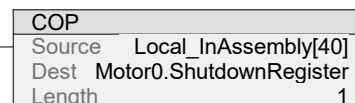
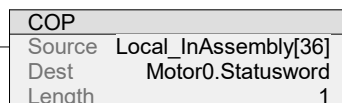
Copy the PWM Duty Cycle values from the IOHUB\_IO UDT to a local version of the output assembly.

3



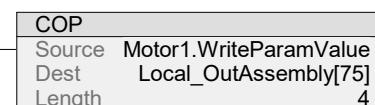
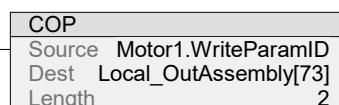
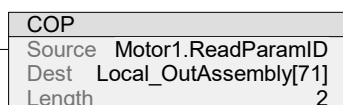
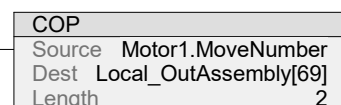
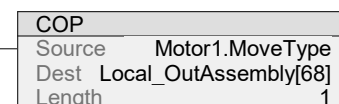
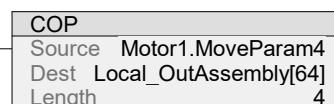
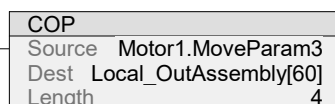
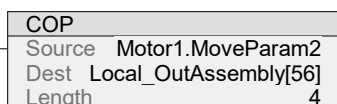
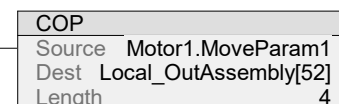
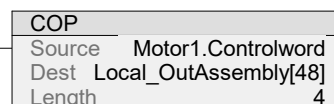
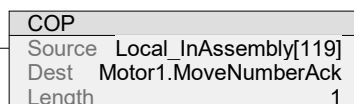
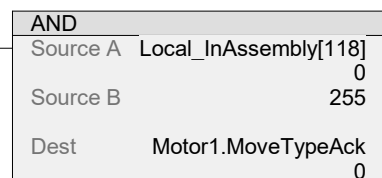
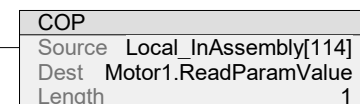
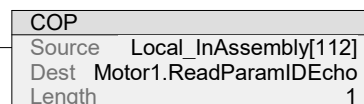
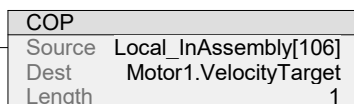
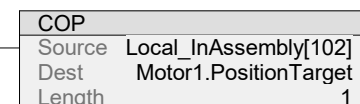
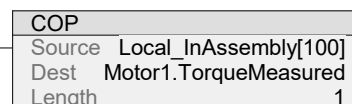
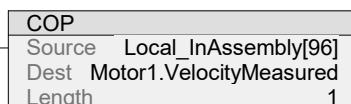
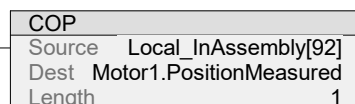
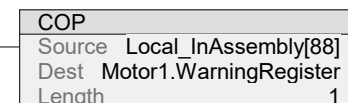
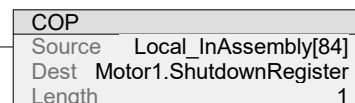
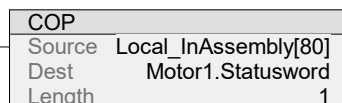
Copy Motor0's input data from the local version of the input assembly into the CPM\_IP\_Motor UDT and copy Motor0's output data from the CPM\_IP\_Motor UDT to a local version of the output assembly.

Data\_Exchange\_Active



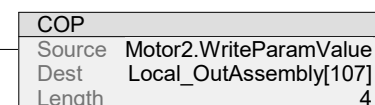
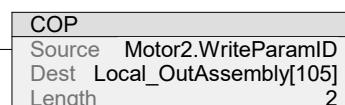
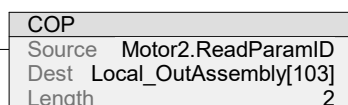
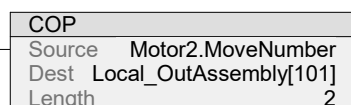
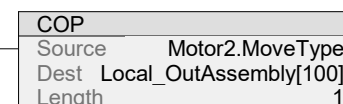
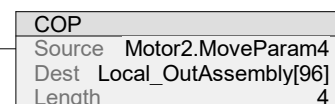
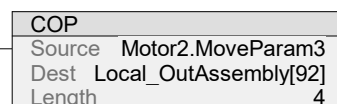
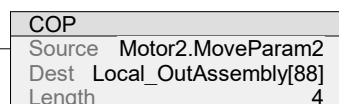
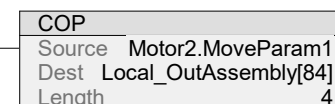
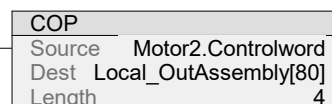
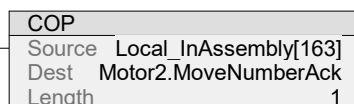
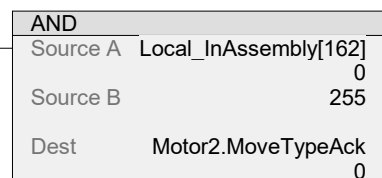
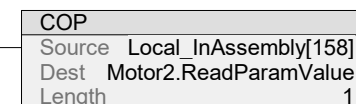
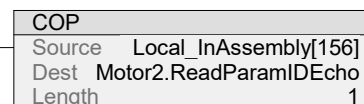
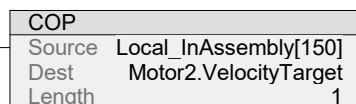
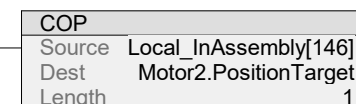
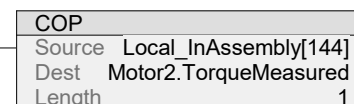
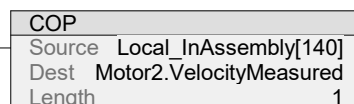
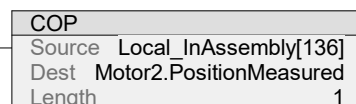
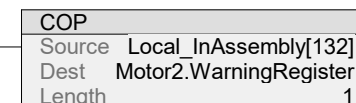
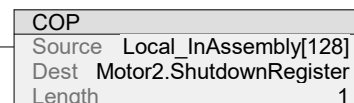
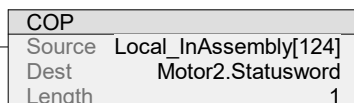
Copy Motor1's input data from the local version of the input assembly into the CPM\_IP\_Motor UDT and copy Motor1's output data from the CPM\_IP\_Motor UDT to a local version of the output assembly.

Data\_Exchange\_Active



Copy Motor2's input data from the local version of the input assembly into the CPM\_IP\_Motor UDT and copy Motor2's output data from the CPM\_IP\_Motor UDT to a local version of the output assembly.

Data\_Exchange\_Active



Copy Motor3's input data from the local version of the input assembly into the CPM\_IP\_Motor UDT and copy Motor3's output data from the CPM\_IP\_Motor UDT to a local version of the output assembly.

Data\_Exchange\_Active

